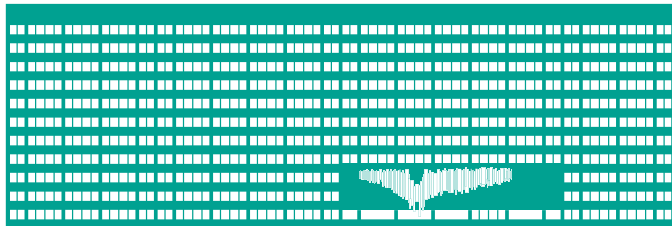


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OF OSTRAVA



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Nice Application of Complete Graph Decomposition

Petr Kovář

joint work with

Dalibor Lukáš, Tereza Kovářová, Michal Kravčenko, Michal Merta

VSB – Technical University of Ostrava, Czech Republic

Seminár z teórie grafov,
11.3. 2021, Bratislava



- 1 Motivation
- 2 Graph theory formulation
- 3 Equivalent formulations
- 4 Known results
- 5 Main result
- 6 A couple of related results and approximations



When solving real life problems

- large $n \times n$ matrix, $n \dots$ millions
- numerical method



Motivation

When solving real life problems

- large $n \times n$ matrix, $n \dots$ millions
- numerical method
- parallelize the computation
- N processes, $N \times N$ blocks (submatrices) B_{ij}

$$\begin{pmatrix} B_{11} & B_{12} & \cdots & B_{1N} \\ \vdots & \vdots & \ddots & \vdots \\ B_{N1} & B_{N2} & \cdots & B_{NN} \end{pmatrix}$$



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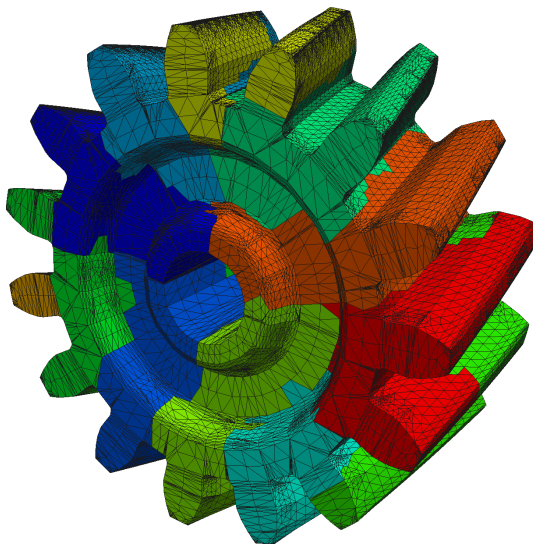
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We have a **dense** matrix!

- distribute N blocks to each processor
- (geometrically) closely related blocks **to the same processor**



Many points, split into N machines.

(ALL)

Decomposing K_n

3 / 24

Parallelization



Parallel machine **without** shared memory.

We prefer parallelization

- load balanced
- memory balanced

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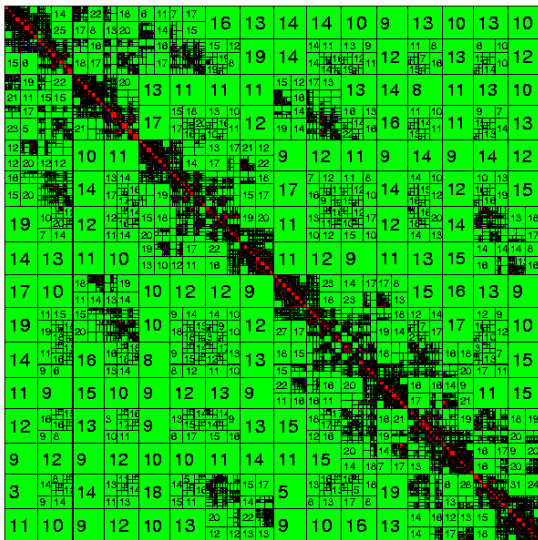
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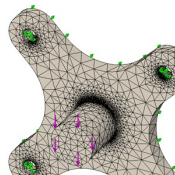
Not all N^2 blocks fit into the memory of one CPU!
(nor all n^2 elements of the matrix)

Block matrix with numbers related to difficulty



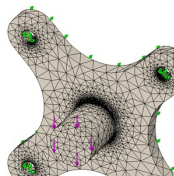
Question: which N blocks on which CPU?

- one diagonal block (longest computation)
- $(N - 1)$ non-diagonal blocks



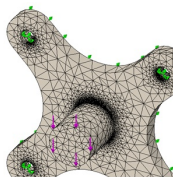
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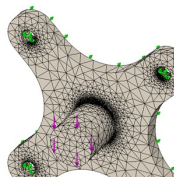


This translates into

- decomposing K_N into N subgraphs G_1, G_2, \dots, G_N
- each with $(N - 1)/2$ edges
- each with as few vertices as possible

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First suppose G_1, G_2, \dots, G_N isomorphic to complete graph.

Graph theory formulation



Decompose K_N into N copies of K_k – dense subgraphs.

Necessary condition: $N = k^2 - k + 1$.



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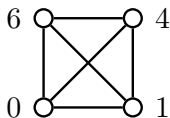
Particularly easy if the decomposition is cyclic:

Definition (Graceful labeling)

Let G be a graph with m edges and a vertex labeling $\lambda : V(G) \rightarrow \{0, 1, \dots, m\}$. The *length* of an edge xy is

$$\ell(x, y) = \min\{|\lambda(x) - \lambda(y)|, 2m + 1 - |\lambda(x) - \lambda(y)|\}.$$

We call f a *graceful* labeling if the set of edge lengths $\{\ell(x, y) : xy \in E(G)\} = \{1, 2, \dots, m\}$.



Graceful and ρ -labeling

The famous Graceful Tree Conjecture: “All trees graceful.”

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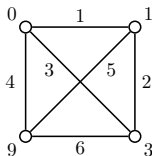
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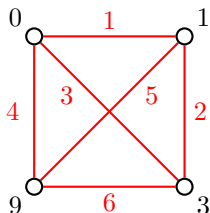
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Theorem (Rosa 1967)

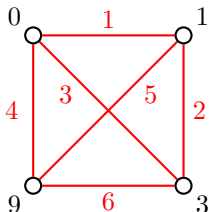
A graph G with m edges allows a cyclic decomposition of K_{2m+1} iff G has a ρ -labeling.





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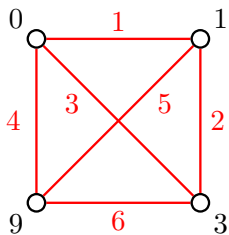
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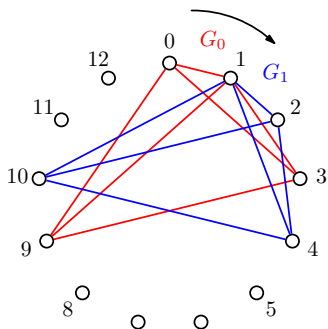
- Not all complete graphs have a ρ -labeling,
- **infinitely many** complete graphs have.



Example



rotate





Definition (perfect difference sets)

A set of integers $\{a_1, a_2, \dots, a_k\} \subseteq [0, N]$ such that every nonzero residue modulo N can be uniquely expressed in the form $a_i - a_j$.



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Example

$\{0, 1, 4, 6\}$ is a perfect difference set for $m = 6$:

$$1 = 1 - 0, 2 = 6 - 4, 3 = 3 - 1, 4 = 4 - 0, 5 = 6 - 1, 6 = 6 - 0.$$



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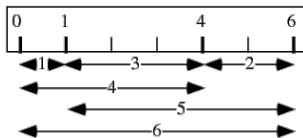
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Perfect ruler (Guy 1994) has k distinct marks s.t. any distance $1, 2, 3, 4, \dots, N$ can be measured. E.g. $0, 1, 4, 6$



Example (Continued...)

Based on the perfect difference set $\{0, 1, 4, 6\}$ for $m = 6$ we can decompose $K_{2m+1} = K_{13}$ cyclically.

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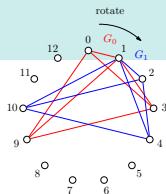
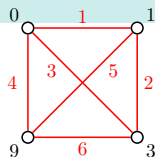
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- the higher N ($N = 13$) the better ratio

Example



	0	1	2	3	4	5	6	7	8	9	10	11	12
0													
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Yet another formulation



Decomposing a complete graph into complete subgraphs – this seems to be a design theory problem.

Definition

A *block design (BIBD)* is a collection B of b subsets (called blocks) of a finite set X of v elements such that any element of X is contained in the same number r of blocks, every block has the same number k of elements, and each pair of distinct elements appear together in the same number λ of blocks.

A symmetric BIBDs are (also known as 2-designs) are denoted as $2 - (v, k, \lambda)$ designs has $b = v$. ($b \geq v$ by Fisher's inequality.)

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In our case:

- $k = k$
- $v = N = k^2 - k + 1$
- $b = N$ (symmetric)
- $\lambda = 1$



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Overview for $k < 100$ on web (Baumert):

http://www.ccrwest.org/diffsets/diff_sets/baumert.html

Main result (2012/2015)



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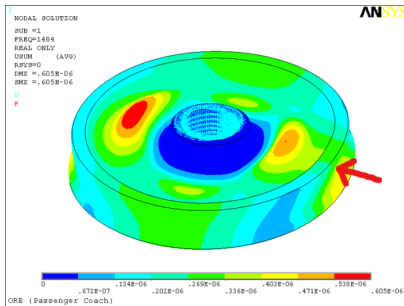
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n	N=31, k=6	N=91, k=10	N=133, k=12
12 288	175 MB, 1 s	200 MB, 1 s	207 MB, 1 s
196 608	353 MB, 53 s	280 MB, 25 s	276 MB, 18 s
786 432	999 MB, 294 s	570 MB, 110 s	535 MB, 99 s
3 145 728			1911 MB, 596 s

Format: average memory [MB], CPU time per process [s]

Motivation: railway wheel noise elimination by profiling



Courtesy of J. Szweda, Department of Mechanics, VŠB – TUO

Additional constructions



Distribution of processes to N CPUs needs not to be balanced (not isomorphic subgraphs).

Typical cluster has 2^t cores, e.g. 128.

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Computational time depends on the largest graph:
preferably few small and a many large dense graphs (complete or “almost” complete graphs).

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By hand up to $n = 31$:

- ρ -labeling of a graph with $(n - 1)/2$ edges
- exceptions $n = 28, 29, \dots$



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Decomposition needs not to be cyclic

$K_7 - K_{3,3}$ decomposes K_{25} , yet no ρ -labeling.
reference?

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- for odd N subgraphs can be isomorphic (exceptions!)
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Example

Decompose K_{147} ($147 = 7 \cdot 21$) into 147 isomorphic subgraphs on 15 vertices.

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Leads to a recursive construction.
Isolated values (case by case).

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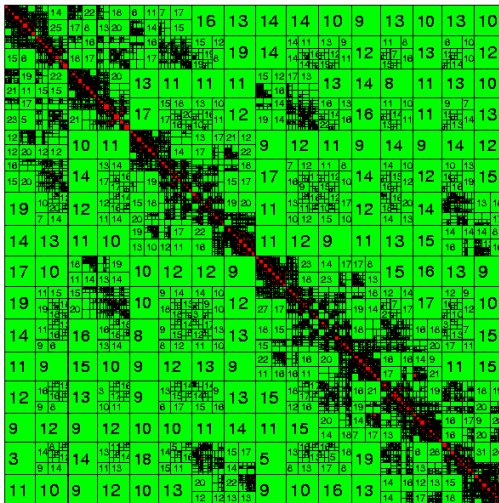
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Theoretical optimum: 25 vertices.

Optimization?



...**balance** the sums among the subgraphs.

(ALL)

Decomposing K_n

23 / 24

Thank you for your attention.